

Conference materials

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## Development of a control algorithm for a fluid flow monitoring system in a microfluidic system

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**Abstract.** Microfluidic systems are widely used in the preparation and analysis of liquid samples in biology, pharmacology and medicine. Each individual device using microfluidic systems differs in structure from others, and the accuracy of fluid control inside is an important factor. In this paper, we will consider the microfluidic system of a DNA analyzer. An algorithm that reads information from flow sensors in real time and transfers it to microcontroller STM32 has been developed for it. The received information was further processed, and on the basis of the received data, a conclusion was drawn about the correctness of the work performed by the device. The error handler, in case of deviation from the process, made the necessary adjustments by sending an error code to the necessary part of the device.

**Keywords:** Microfluidic system, control algorithm, fluid control, flow sensor, DNA analysis

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Материалы конференции

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## Разработка алгоритма контроля системы мониторинга потока жидкости в микрофлюидной системе

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**Аннотация.** В данной работе рассматривается микрофлюидная система анализатора ДНК. Для нее был разработан алгоритм, считывающий информацию с датчиков потока в режиме реального времени и передающий ее на микроконтроллер STM32. Полученная информация подвергается дальнейшей обработке и на основании полученных данных делается вывод о правильности работы прибора. Обработчик ошибок при необходимости вносит необходимые коррективы, отправляя код ошибки в нужную часть устройства.



**Ключевые слова:** Микрофлюидная система, алгоритм контроля, контроль потоков, датчик потока, анализ ДНК

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## Introduction

At present, with the development of scientific and technological progress, much attention is paid to various research methods [1–8]. This is especially true in the context of an increase in the influence of various negative factors on biological systems [8–14]. Therefore, for the study of biological systems, as well as condensed media associated with them, a large number of methods have been developed [2–5, 7–9, 15–21]. They have various advantages and disadvantages. This determines their direct application.

The sequencing method of DNA is currently extremely demand for solving of the different tasks in medicine and biology [22–27]. For example, sequencing methods widely used in different medical researchers related with viruses and diseases.

Thus, in sequencing devices, it is necessary to transfer a given volume of liquid at a given speed for the correct analysis.

The performance of microfluidic systems depends on monitoring and adjusting the fluid flow in them. The various sensors or flowmeters are performing this task, in particular, a fluid flow sensor [28–31]. Information from the sensor must be read and processed during the entire operation of the hydraulic system.

Therefore, it is important to create an optimal algorithm that is able to carry out the task throughout the entire sequencing process. Also, an important part of this algorithm is the logging of all received data to eliminate and troubleshoot microfluidic systems.

As a consequence of this, the algorithm described above serves not only as a way to control and adjust the hydraulic system, but also to collect data for post-processing of the experiment.

## Structure of the algorithm

The fluid in the microfluidic system of the sequencer moves through thin capillaries using a pump. The pump, having received a command from the control algorithm, adjusts the direction and speed of the fluid supply. To check the correctness of its operation, a liquid flow sensor is installed in front of the element holding chemistry reactions for sequence.

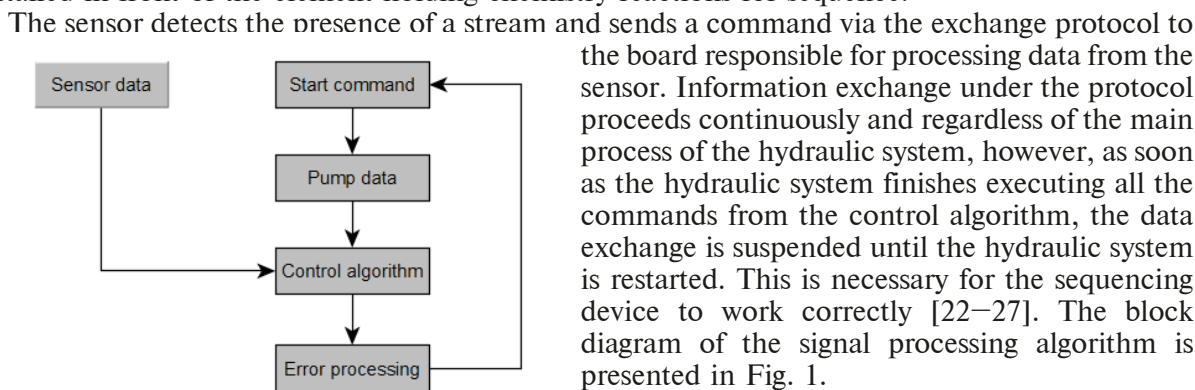


Fig. 1. Data processing algorithm

The data exchange between the sensor control board and the fluid flow sensor is carried out using the symbols of the binary system, where the unit corresponds to the state of the sensor in which the fluid flow is fixed, and zero corresponds to the state in which the sensor does not observe the flow. Obviously, this information is not enough to control the algorithm, so the data received from the sensor must be compared with what is expected to be seen at the present moment. In other words, starting its work, the pump sends information about how long it is necessary to observe the fluid flow at the sensor installation point. Thus, having received a signal from the pump and the sensor, it is necessary to compare them.

As shown in Fig 1, when a command is received from the program controlling the device, the pump starts its work, while sending the necessary information to the control algorithm. At the same time, the interrogation of the flow sensor begins. In case of discrepancy between the expected and accepted values from the flow sensor, this data goes through the error processing algorithm.

Further, the processor can continue the operation of the device, if the error was not critical, or suspend the experiment by calling the user's dialog box with a choice of further actions.

The entire process of polling the sensor and the operation of the hydraulic system is logged with time stamps. Thus, if necessary, it could be determined the cause of the failure by examining the relevant documentation.

### Realization of algorithm in hydraulic test model

The main aim of developing described algorithm is to use it in sequencing systems. To ensure that described algorithm correctly works the hydraulic system test model was developed. This system is shown in Fig. 2.

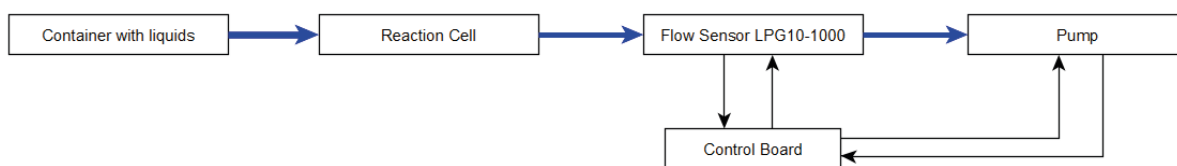


Fig. 2. Block scheme of hydraulic system test model; blue lines correspond to liquid capillaries, black lines to data exchange

One of the parts of the hydraulic system test model is flow sensor LPG10-1000. The parameters of this sensor are presented in Fig. 3. It is necessary to define flow state (logical unit corresponds to fixed fluid flow, logical zero to absence of fluid flow) for algorithm to work correctly. Because of described sensor could perform information about flow rate, it is necessary to determine flow rate threshold value. The threshold value was equalized to 50  $\mu\text{l}/\text{min}$ , due to the LPG10-1000 characteristics. Thus, the flow rate values below the determined threshold are defined as logical zeroes for algorithm.

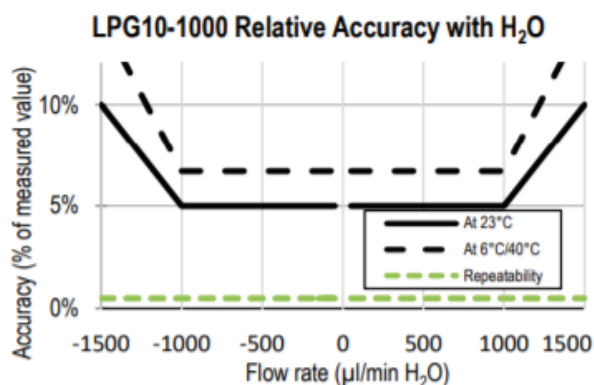


Fig. 3. LPG10-1000 sensor accuracy and repeatability (% of measured value) across the sensor's flow range

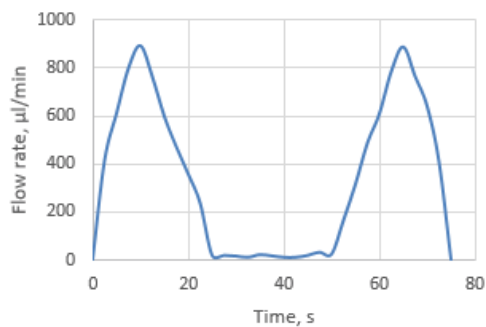


Fig. 4. Visualization of flow rate data from sensor

In developed test model, the control algorithm is performed via control board with microprocessor. The board is connected to pump via UART protocol and to flow sensor via I<sup>2</sup>C protocol. The connection between the board and the pump is necessary to get data from pump (pump status – in work or not).

The control board sends command to pump to start aspirating then control board receives the answer from pump with its status. While pump is aspirating the flow sensor is exchanging its data with control board every 1 second. That provides control of flow status in every iteration. The data from pump and flow sensor is processed on

control board and goes through error processing afterwards. It is necessary to avoid issues such as value below threshold on flow sensor while pump is aspirating.

### Results

As a result, the algorithm was implemented in hydraulic system test model and the acquired information is confirming correctness of described algorithm. This information shows correlations between flow rate from flow sensor, working state of pump and real aspiration process as shown in Fig. 4.

### Conclusions

The developed algorithm allows to control the correct operation of the hydraulic system of the sequencing device. If necessary, the algorithm has the ability to suspend the operation of the entire device, or a specific part thereof, notifying the user at the same time, and will wait for further instructions.

Moreover, developed algorithm can be used not only in sequencing system which described below, but also in another types of hydraulic systems, where is necessary to control the flow rate or flow status.

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